

Satellite-Based Detection of Fog and Very Low Stratus

A High-Latitude Case Study Centred on the Helsinki Testbed Experiment

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 - The Problem
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 - Helsinki Testbed
 - Satellite Algorithm
- 3 Tests and Analysis
 - Data Comparison
 - Conclusions



Motivation

4 killed in 250-vehicle pileup in Italy

Fog is blamed in high speed chain reaction crash

PADOVA, Italy (CNN)

A high-speed chain reaction crash Thursday involving 250 vehicles on a fog-bound highway in northeastern Italy, left at least four people dead and scores of others injured, officials said.

Scores of crumpled and burnt cars, trucks and buses were piled behind one another on both sides of the four-lane road linking Padua and Bologna. Some vehicles plunged down a grass bank into a ditch. Some of the victims were reported to have burned to death. Emergency crews rushed to the scene, sifting through wreckage for possible survivors.

Police said fog had reduced visibility to less than 60 yards (200 meters) when the chain reaction crash began about 9 a.m.

The first collision occurred on the southbound side of the road but there were further crashes in both directions. Some traffic on the northbound side was stopped for hours.

With both lanes blocked, emergency vehicles had trouble reaching victims. The fog was so thick, helicopters could not land to remove the injured.

A truck carrying uranium was in the midst of the wreck, but it was not clear if it posed a hazard.

Web posted Saturday, June 19, 2004

Heavy fog leads to fatal boat crash

Signs of alcohol found in boat that sped head-on into pier; Autopsy planned

By RICHARD HARROL
Staff writer

A 20-year-old Saugatic

WORLD

Fog blamed in Uzbek plane crash

Wednesday, January 14, 2004 Posted: 10:06 PM EST (03:00 GMT)

TASHKENT, Uzbekistan (AP) — An airliner was making its second attempt to land in heavy fog when it crashed just short of the runway, killing all 37 people on board, including the top U.N. official in this Central Asian country.

Four foreigners were among the passengers on the Uzbekistan Airways flight that crashed Tuesday evening, Prosecutor General Rashid Kadyrov said.

They were Richard Conroy, a



Fog led to a 200-car pileup on the Long Beach (Calif.) freeway that left several

BBC NEWS WORLD EDITION

Last Updated: Thursday, 10 July, 2003, 11:52 GMT 12:52 UK

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Crash pilot 'confused by fog'

A motor racing millionaire may have become confused just before the plane he was piloting crashed in thick fog killing all five people on board, a report has said.

Guernsey racing promoter Brian Kreisky was taking family and friends on a festive break to Majorca when the light aircraft crashed on 23 December, 2000.

The Beech 200 plane had just taken off from Blackbushe airport near Camberley, in Surrey, when the left propeller lost its power, a report from the Air Accidents Investigation Branch (AAIB) said.



Mr Kreisky was flying family and friends to Majorca for Christmas

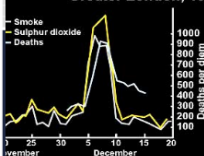


A passenger on the flight of Holland sustained minor injuries and was treated and released at the Holland Community Hos



Uzbek officials inspect the crash site at Tashkent airport.

Greater London, 19



Aims

Fog detection system should offer

- High spatial resolution (fog margins)
- High temporal resolution (nowcasting)
- Long time series (climatology)



Aims

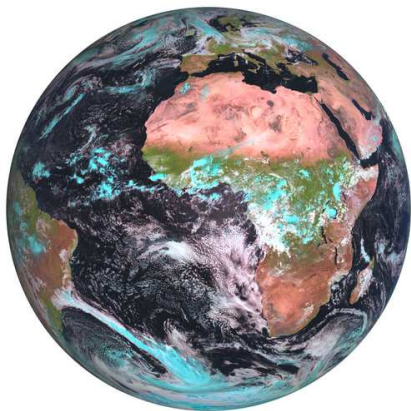
Fog detection system should offer

- High spatial resolution (fog margins)
- High temporal resolution (nowcasting)
- Long time series (climatology)

Only geostationary satellite data suited!



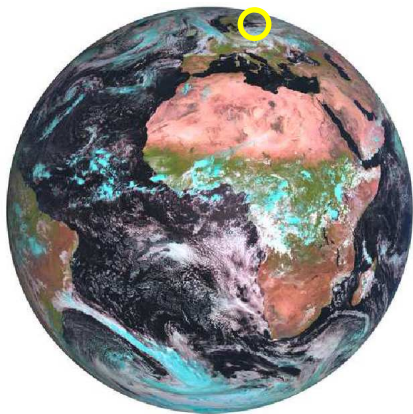
Satellite system: Meteosat 8 SEVIRI



- 3 km spatial resolution
- 15 min repeat rate
- 11 spectral channels
- Operational since 2004



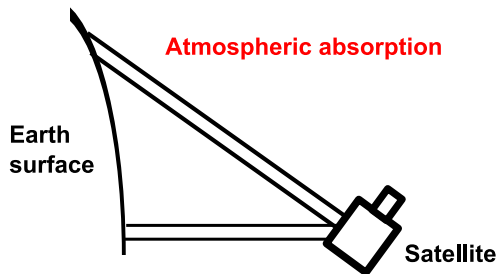
High Latitudes: Finland



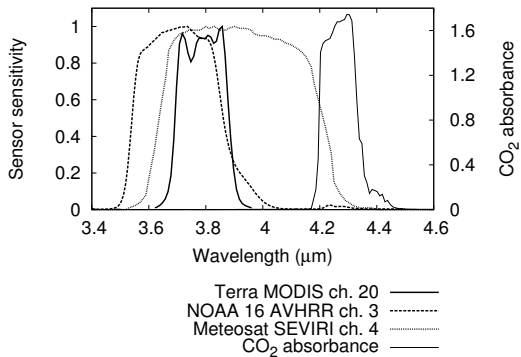
- Latitude southern Finland:
 $\approx 61^\circ$
- Satellite zenith angle:
 $\approx 70^\circ$
- Reduced spatial resolution
- Low solar elevation
- Enhanced atmospheric effect



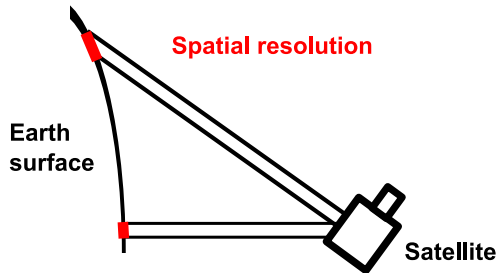
High Latitudes: Difficulties



High Latitudes: Difficulties



High Latitudes: Difficulties



Research Question

Problem

Is the detection of fog and very low stratus possible

- *from a geostationary platform*
- *at high latitudes?*

To be investigated with detailed measurements.



Helsinki Testbed

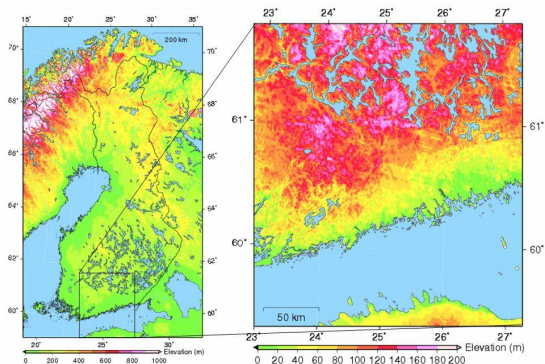
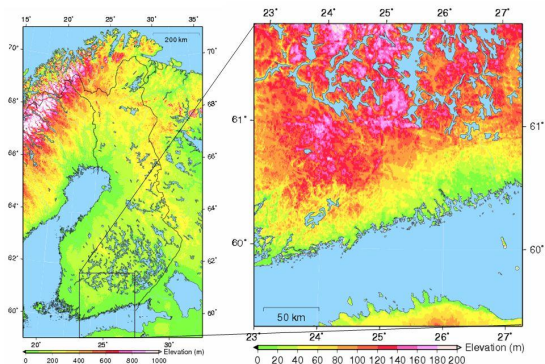


Figure: J. Poutiainen, 2006



Helsinki Testbed



- 2005–2007
- Mesoscale weather research
- System integration
- Model development
- Data and info on www.fmi.fi/testbed

Figure: J. Poutiainen, 2006



Measurements

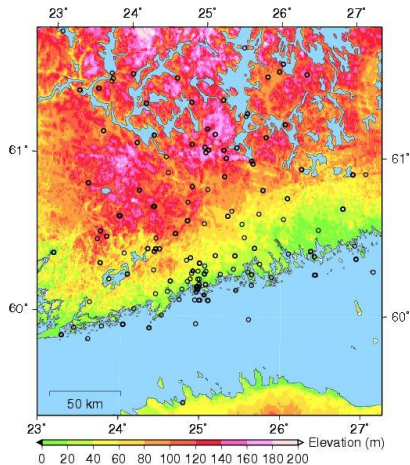


Figure: J. Poutiainen, 2006

- Targeted measurements for
- Nowcasting applications
 - Precipitation type
 - Sea breeze
 - Convection
 - *Stable boundary layer*



SOFOS

SOFOS – Satellite-Based Operational Fog Observation Scheme

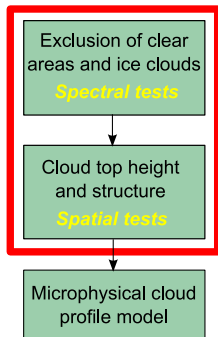
Fog as a

- *cloud*
- in the *water phase*
- *low* above ground
- with a *stratiform* surface
- impairing visibility *at the ground*.

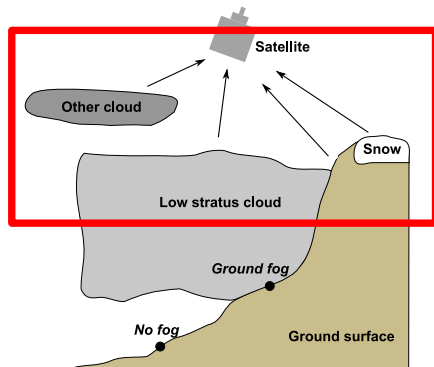


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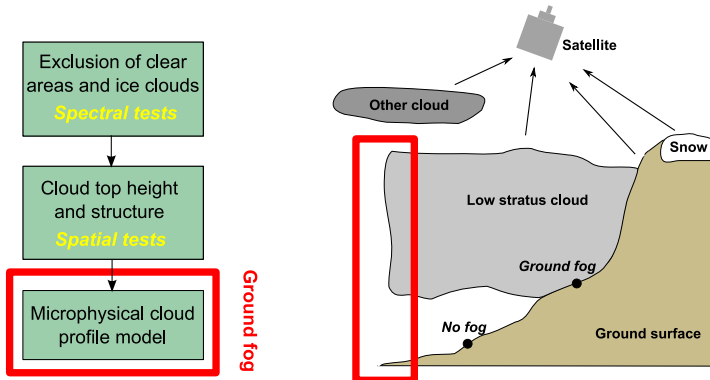


Very low stratus



SOFOS

SOFOS – Satellite-Based Operational Fog Observation Scheme



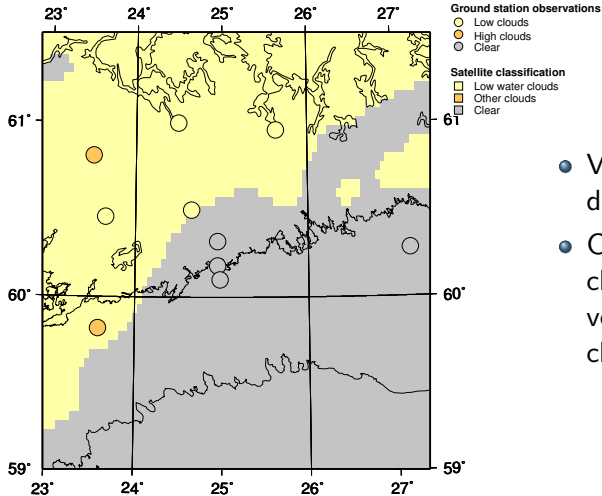
Test Procedure: Data Selection

12 days, November 2005 – February 2006

- Data availability
- Data quality
- Includes fog / low stratus situations



Test Procedure: Point/Pixel Comparisons



- Visibility and ceilometer data for low cloud presence
- Compared with satellite classification (no cloud / very low stratus cloud / high cloud)



Test Procedure: Contingency Tests

	Observation Yes	Observation No
Classification Yes	A	B
Classification No	C	D

Hit Rate: $HR = \frac{A}{A+C} \quad [0 \dots 1]$

False Alarm Rate: $FAR = \frac{B}{A+B} \quad [0 \dots 1]$

Critical Success Index: $CSI = \frac{A}{A+B+C} \quad [0 \dots 1]$



Test Results: By Day

Indicator	Value	Best	Worst
HR	0.66	1.00	0.52
FAR	0.25	0.00	0.67
CSI	0.54	1.00	0.31
n	9374		

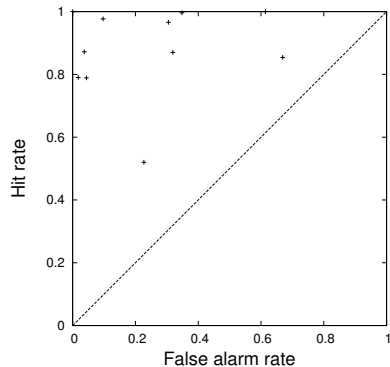


Figure: Results by day



Test Results: By Station

Indicator	Value	Best	Worst
HR	0.66	0.78	0.51
FAR	0.25	0.00	0.60
CSI	0.54	0.77	0.36
n	9374		

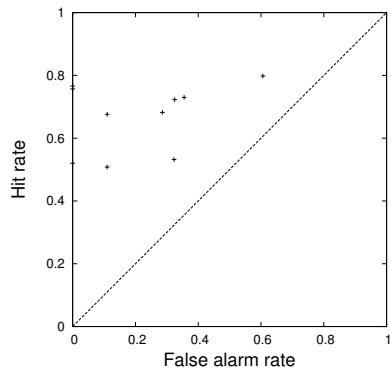


Figure: Results by station



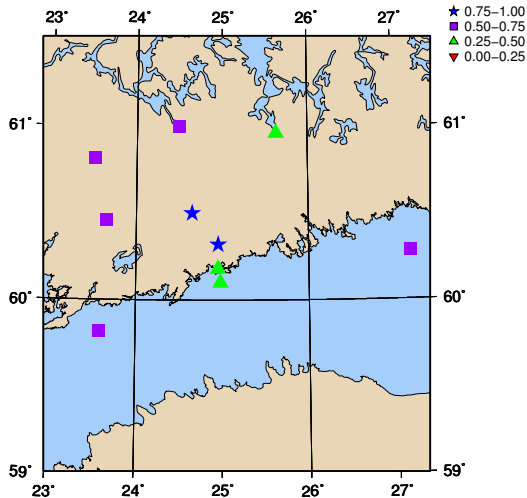
Analysis

Possible reasons for misclassifications:

- Missed situations:
 - Cloud overlap
 - Low cloud cover
- False alarms: Station data not representative of pixel
- Station data quality (Visibility and ceiling don't always agree)



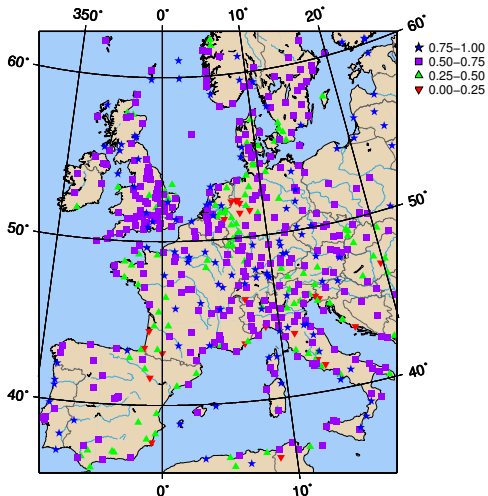
Test Results: CSI Distribution



- Lowest category not present
- No obvious spatial pattern



European Context: CSI Distribution



- 583 METAR stations
- 24 days 2nd half 2005
- 1030 satellite scenes
- *No latitudinal effect!*

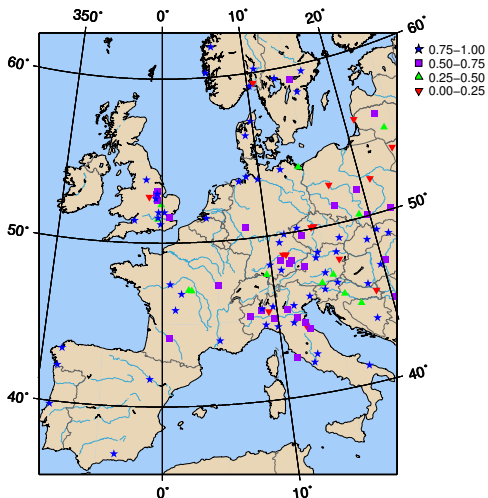


Conclusions

- High latitude detection of very low stratus works well
- Small-scale situations may be missed
- Coordinated measurement efforts useful



Outlook



- Ground fog will be tested for Helsinki testbed
- Qualitative analysis of cases to follow



Contact

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www.fmi.fi/testbed

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